
NIRSPEC

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NIRSPEC Software Programming Note 02.01 Graphical User Interface

1 Introduction

This programming document describes the implementation of the NIRSPEC Graphical User Interface (GUI). The GUI is a DataViews-based X application. A quick guide to learning DataViews is included in the GUI design note NSDN0501.

2 Overview

All the GUI source code is located in the directory `/kroot/kui/xnirspec`. In addition, the DataViews `.v` view files are located in `/kroot/kui/xnirspec/views`, the `.lay` layout files in `/kroot/kui/xnirspec/layouts`, and `.dr` drawing files in `/kroot/kui/xnirspec/drawings`.

The GUI source modules are listed as follows:

<code>xnirspec.c</code>	- main program
<code>dataviews.c</code>	- routines to handle X display using DataViews
<code>create_interest.c</code>	- routines to create keyword interest for broadcast
<code>callbacks.c</code>	- callbacks for keyword broadcast
<code>misc.c</code>	- miscellaneous routines
<code>xnirspec.h</code>	- NIRSPEC client definitions
<code>dataviews.h</code>	- DataViews definitions
<code>nirspec.h</code>	- NIRSPEC server definitions

3 Program Description

3.1 header files

The header file **xnirspec.h** defines various macros and declares program variables as memory buffers to hold the DataViews variable descriptors. Several data structures are also defined, along with public function prototyping.

The header file **dataviews.h** defines data structures for DataViews displays, menus and pop-ups.

3.2 xnirspec.c:

The module **xnirspec.c** contains **main()** of the GUI program. Besides several standard header files, it includes "**xnirspec.h**" and the generic KTL definition header file "**ktl.h**". A few global variables are declared which can be accessed by other source modules as external variables:

```
int Simulate = FALSE;          /* simulation mode flag          */
int NoDCS = FALSE;            /* no DCS server running flag    */
int Quit = FALSE;            /* program quit flag             */
int ServerOnHost = FALSE;     /* flag indicating server is on the host */
KTL_HANDLE *khand;           /* handle to the NIRSPEC keyword library */
KTL_HANDLE *dcs_khand;       /* handle to the DCS keyword library   */
```

main() has the following program control flow and structure:

- Check arguments
- Disable Ctrl-C
- Check whether client and server on the same machine
- Set up error logging
- Make connection to NIRSPEC keyword library
- Create keyword broadcast interest list
- Make connection to DCS keyword library if specified (normally not).
- Initialize global variables
- Initialize X displays
- Loop to process X, and KTL events
 - Create a fd set consisting of X socket and KTL fd
 - Block until an X, or KTL event arrives
 - Handle events
- Close X displays
- Close connection to DCS keyword library
- Close connection to NIRSPEC keyword library

Some explanations are given below:

1. The function **main()** accepts up to three command line arguments. They can be "**-s**", "**-nodcs**" and "**-noql**".
2. Ctrl-C is disabled to prevent abnormal exit of the program.
3. The flag **ServerOnHost** indicates whether the client is running on the same machine as the NIRSPEC server program. If it's **FALSE**, a remote data transfer may be required for the quick-look display.
4. The message logging is performed by the Unix **syslog()** function.
5. Depending upon the value of the flag **simulate** which is set by the argument "**-s**" in **main()**, the program connects to either the real instrument server or the simulation mode server.
6. The function **init_globalvars()** in **misc.c** is called to set various program flags and initialize variables by reading keyword values from the server.
7. The CLI program is no longer run.
8. **DV_init()** from **dataviews.c** initialize DataViews displays. The X socket file descriptor **x_fd** is returned from the macro **ConnectionNumber()** for the asynchronous I/O in the event loop.
9. A socket connection is opened between the GUI and quick-look to pass information like frame arrival.
10. The core of **main()** is the event loop to process events from the KTL RPC server and events from the X socket, CLI socket and quick-look socket. Because the program must be able to handle several different file I/O sources, an asynchronous I/O multiplexing scheme is implemented for the event loop using the UNIX **select()** function call. **select()** examines an I/O file descriptor sets to see if any of the file descriptors are ready for reading, writing, or have an exceptional condition. A fd set consisting of various fds is created in the beginning of the loop as follows:

```
FD_ZERO( &readfds );  
ktl_ioctl( khand, KTL_FDSET, &readfds );  
FD_SET( x_fd, &readfds );  
FD_SET( cli_fd, &readfds );  
FD_SET( ql_fd, &readfds );
```

The macro `FD_ZERO()` initializes a file descriptor set to the null set. Note that because the KTL call `ktl_ioctl(,KTL_FDSET,,)` automatically clears a fd set, it must be placed before the macro `FD_SET()`.

The next code segment in the event loop is to block the process indefinitely until an event arrives:

```
if ( (select( maxfds, &readfds, NULL, NULL, NULL ) == -1 ) &&
      errno != EINTR) ) {
    syslog( LOG_WARNING, "select() failed." );
}
else {
    if ( FD_ISSET( x_fd, &readfds ) ||
          FD_ISSET( ql_fd, &readfds ) ) {
        /*
         * Handle X events
         */
        if ( FD_ISSET( x_fd, &readfds ) )
            DV_handle();
    }
    /*
     * Invoke KTL event handler
     */
    else
        KTL_DISPATCH( khand );
}
```

`select()` returns if any of the fds is ready for reading. The program calls the macro `FD_ISSET()` to determine which fd is ready, and then invokes a specific function routine to perform the request operation.

11. When `main()` exits, RPC and socket connections are closed by clean-up routines.

3.3 dataviews.c:

The routines in `dataviews.c` handle DataViews displays. They can be divided into different groups in terms of functions they perform as listed below:

High-level routines:

<code>DV_init()</code>	- initialize DataViews
<code>DV_handle()</code>	- handle DataViews events
<code>DV_close()</code>	- close DataViews displays
<code>DV_updateScreen()</code>	- update display screen
<code>DV_updateCurrentObs()</code>	- update current observing parameters
<code>DV_expStatus()</code>	- update exposure status display

Routines to perform initialization:

create_screen() - create a window and load the view to be displayed
drawport_init() - load the view, get the objects and the variables, and create a drawport to be used
drawport_new() - load a view, create a new drawport and display.
vdps_init() - initialize variable descriptors
vdps_rebind() - modify the variable descriptor to use our own program variable as the memory buffer
input_objects_init() - initialize input object components and post service result request

Routines to display pop-ups:

popup_draw() - add a popup to the active drawport's view
popup_delete() - delete popup objects from the view
popup_deleteAll() - delete all popup objects from the view

Routines to display sub-views:

subview_load() - load the dialog view, get the interesting objects and create a drawport
subview_draw() - draw subview and handle events
subview_erase() - Erase the subview and repair any damage to other views caused by the erasure

Routines to display dialog boxes:

get_automsg() - display message
get_message() - display a single line message
get_mmessage() - display multiple line message
get_confirm() - get confirmation
get_input() - get an input value

DataViews event callback routines:

menu_inst_setup_callback()
.....

The high-level routines provide a DataViews interface layer to NIRSPEC application routines. The routines `DV_init()`, `DV_handle()` and `DV_close()` are briefly discussed below:

Display *DV_init(void):

This initialization routine performs the following functions:

- Initialize DV-Tools
- Initialize the real-time name:data look up table
- Make entries for the name buffer pairs defined in `data_table`
- Initialize variable descriptors
- Initialize display
- Initialize input objects
- Initialize all dialog subviews
- Extract environment variable values
- Get exposure status objects for exposure update

void DV_handle(void):

This routine consists of an event loop to handle various X events as shown below:

```
/*
 * Poll event queue for locator events
 */
while ( location = VoloWinEventPoll( V_NO_WAIT ) ) {
    current_drawport = TloGetSelectedDrawport( location );
    current_screen = VoloScreen( location );

    VUserHandleLocEvent( location );

    /*
     * Return event types
     */
    switch ( VoloType( location ) ) {
        case V_RESIZE:
            TscReset( current_screen );
            break;

        case V_EXPOSE:
            TscRedraw( current_screen, VoloRegion( location ) );
            break;

        case V_KEYPRESS:
            break;

        case V_BUTTONPRESS:
            handle_button_press( location );
            break;
    }
}
```

```

        case V_BUTTONRELEASE:
            break;

        default:
            break;
    }

```

For example, a button press will invoke **handle_button_press()** to perform certain function. The loop updates observing setup parameters by calling **update_obsparam()**. The graphic displays are updated by **TdpDrawNext()** at the end of each loop.

void DV_close(void):

This routine is rather simple. It destroys each view and drawport and closes each screen. It then frees the data table of "name:buffer" pairs. That source code is listed below:

```

for ( i = 0; i < NUM_WINS; i++ ) {
    TdpDestroy( dv_drawport[i] );
    TviDestroy( dv_view[i] );
    TscClose( dv_screen[i] );
}

table = data_symbol_table;
while ( VTstlen( table ) > 0 ) {
    node = VTstsnget( table, 0 );
    varname = VTsnkey( node );
    S_FREE( varname );
    VTstsnremove( table, node );
}
VTstdestroy( data_symbol_table );

TTerminate();

```

3.4 create_interest.c and callbacks.c:

When the GUI receives a keyword sent from the NIRSPEC server via broadcast, a user-defined callback function will be invoked by **KTL_DISPATCH()** to perform certain function. Whether the program should respond to a NIRSPEC keyword broadcast from the server is defined by **create_nirspec_interest()** in **create_interest.c** using the defined macro **EXPRESS_INTEREST**:

```

#define EXPRESS_INTEREST( keyword, keyword_callback )           \
    context.callback = (int(*)()) keyword_callback;           \
    if (ktl_read(khand,KTL_CONTINUOUS|KTL_NOPRIME,keyword,0,0,&context)<0) { \
        fprintf( stderr, "xnirspec: %s\n", ktl_get_errtxt() ); \
        exit( -1 ); \
    }

```

For example, `EXPRESS_INTEREST("outdir",outdir_callback)` will allow the broadcast of the keyword “**outdir**” to invoke a callback function.

A callback routine performs a user-defined function when a keyword broadcast happens. The follow is the callback function for the keyword “**outdir**”:

```
void outdir_callback( keyword, user_data, call_data, context )
char *keyword;          /* keyword */
void *user_data;       /* unused */
KTL_POLYMORPH *call_data; /* contains new value */
KTL_CONTEXT *context;  /* command context (unused) */
{
    strcpy( VdpBuf_datapath[0], call_data->s );
    strcpy( ObsSetup[0].datapath, call_data->s );
    DV_updateScreen( SCREEN_SPEC );
}
```

As can be seen, this callback copies the new **outdir** value to a display variable and updates the DataViews display.

3.5 misc.c:

`misc.c` contains miscellaneous functions which include routines to control exposures, routines to make a file name, routines to manipulate instrument configuration file, and other routines. They are listed below:

<code>exp_start()</code>	- start an exposure
<code>exp_abort()</code>	- abort an exposure
<code>exp_end()</code>	- finish an exposure
<code>exp_done()</code>	- finish an exposure and notify quick-look display
<code>exp_updateStatus()</code>	- update exposure status
<code>write_obsParam()</code>	- write observing parameters using <code>ktl_write()</code>
<code>write_abort()</code>	- write the "abort" keyword
<code>Filename_get()</code>	- get the current image file name
<code>Filename_make()</code>	- make an image file name by incrementing file number
<code>config_save()</code>	- save instrument configuration file
<code>config_read()</code>	- read configuration file and re-configure instrument
<code>init_globalvars()</code>	- initialize global variables
<code>get_hostname()</code>	- get the host domain name